



Before mounting the Merlin on the **arm**, we suggest turning the bottom **wheel** until the **rod end** (14) is all the way in. Then turn the top most **wheel** in the opposite direction (out) until about 3 threads are showing. That will lean the **arm** slightly away from the operator, allowing for proper use.

When switching the **arm mounting** to the opposite side for left or right-handed operation, be sure to re-adjust these **wheels** so the 'top' attachment is out and be sure the 'bottom' one is always in.

## DON'T OVEREXTEND EITHER ATTACHMENT SCREW AS THE ARM WILL EVENTUALLY COME APART FROM THE MOUNTING BLOCK.

To operate the Merlin on the right side of the body, remove the **pin** from **arm** as shown in the photo detailing **wheels** (13). Turn the **socket block** upside down, insert **pin** again. Then, lay the **vest** down on a table. Loosen and remove all four **thumb screws** holding the **arm bridge** (9) to the **vest** and turn the **bridge** around 180 degrees so it rests on the left side of the **vest** center. (right of center as you look at it) Lock it in place again using **thumb screws**.

Insert the **arm**. Tighten the bottom **wheel** all the way and loosen the top one a few turns and you are set. This mode frequently offers an easier view of the camera's flip-out viewfinder that's used when operating the Merlin system.



There is an **arm restraint strap** (15) on your Merlin **vest**. To capture the **arm** from moving about while the Merlin is not mounted, open the **strap**. Draw it away from the **vest**. Tuck the Steadicam **arm** up against the **left vest spar** area near the **strap**. Wrap the **strap** around the **arm** and capture it against itself. Now the **arm** cannot move, but can quickly be freed.



Your Steadicam Merlin Vest/ Arm system comes with an **all-metal gimbal** (16). As per instructions in the Merlin for adjusting your **gimbal**, remove your Merlin **gimbal** and replace it with this new one. There is no need to go back and forth. Using this new **all-metal gimbal**, you can use the Merlin on or off the Arm/Vest system.



To mount the Merlin onto the **arm**, hold the **arm** still with your right hand. Grasp the Merlin **gimbal/handle** (16) with your left hand and lift off of the optional **docking bracket**. Line up the **hole** in the bottom of the Merlin **handle** with the **arm post** (17) in the Steadicam **arm**. Rest the Merlin onto the **arm post**.



To adjust the lift delivered by your Steadicam Merlin **arm**, lower the **arm** by pushing down with the left hand until the **arm section** closer to your body is just above horizontal. This is the "sweet spot" for turning the **lift adjust knob** (18). Turn to the right to increase lift. Turn to the left to decrease lift. When that section appears to feel as though it is floating flat – parallel to the ground – make the identical adjustment to the other section.



When the Merlin Vest/ Arm system is properly adjusted, both **arm** sections are parallel to the ground. The Merlin Handle is held in the right hand. The left hand operates the Merlin **gimbal** as usual. Practice proper standing, walking and hand position. See the Merlin DVD for further operating tips.

# STEADICAM<sup>®</sup> MERLIN

Arm and Vest Quick Start Card



Remove the **straps** from the bag. There are two that are 12" long. These are the **shoulder straps**. Attach to both shoulder areas as shown in the photos, using the **keeper** near the end.

Two straps are 22" long. One is 18" long. Attach one of the 22" straps to the right side of the **waist panel** of the **vest**. Overlap the second 22" **strap** on top of it. Pass the open end of that second 22" **strap** through the **keeper**, and fold it back on itself. This is your **waist strap** length adjustment. Then take the 18" strap and pass it through the **keeper**. Follow directions to affix to **waist panel**.



After you put the **straps** in place, the **vest** will look like this.



Fold back the **right shoulder strap** (1), so that the **right-hand pad clasp** (2) is able to line up with the right top of the **chest spar** (3). Press the **spar end** against the hook area on the **pad clasp**. Close the **shoulder strap** over onto the top of the **chest spar**. This insures a very tight grasp. Do not repeat this step on the left hand side-it is left open until you put the **vest** on.



Draw the **left chest** (7) **strap** across the **chest bridge** (6), while at the same time holding firmly onto the **waist panel** (8). Make sure **chest spar** is vertical to your body as you do this, not crooked. Press the **left chest strap** on top of the **right chest strap** on the **chest bridge**. The **vest** is now 2/3 fitted to your body.



The **waist strap** should look like this as you reach behind with your left hand to grasp it. The long smooth part is pressed into the right side of the **waist panel**. The adjustable part is grasped in the left hand.

Hold the **waist panel** with the right hand. Draw the **waist strap** firmly around your back and press it down onto the left side of the **waist panel**.



From the back the **straps** are symmetrical, insuring an even fit with good distribution of the weight.



Insert the **connecting pin** through the sections as shown. Insert it so that the **ring** is on the top of the **arm**.



Insert the **arm** into the **vest socket block** (12). Holding the section shown in your right hand, guide the **arm socket** into the **vest socket block**. Line up the **pin** to the **hole**.



Using the left hand, gently guide the **socket** into place.

Steadicam Merlin Vest and Arm system. Step by step you will create the Steadicam shots of which you have always dreamed.

## Merlin Arm & Vest



Pull the **right chest strap** (4) through the **keeper** (5) and affix to the back of the **vest**. This will take a few tries back and forth. The goal is to have both **chest straps** symmetrical, and to have the upper part of the **vest** held firmly against the torso.



Take the portion of the **right chest strap** (4) that will hold the right side of the **vest** and press it against the **chest bridge** (6). Slip your right arm through the armhole and pull the **vest** on until it is resting on your shoulders.



Repeat the **shoulder clasp** maneuver on the left side, pressing the **left shoulder strap** onto the left top of the **chest spar**. Line up the **left chest strap** with the **chest spar**. Attach it.



From the front, the **chest spar** is straight. The **straps** snugly fit along the chest and waist. The **shoulder pads** of the **vest** are resting on your shoulders.



To move the **arm bridge** along the **vest spar** when the **vest** is made shorter, lay the **vest** down. Loosen all **four thumb screws** until they come out. Remove the **arm bridge** and move it lower on the **vest spar**, lining up the **holes** in the **bridge** with **holes** in the **spar**. Re-attach using the **four thumb screws**.

The length of your **vest** can be adjusted. Loosen the **thumb screws** located on the bottom area of the **arm bridge** (9). They hold the **bridge** on the **vest spar** and also permit for vertical adjustment. All four **screws** should be loosened no more than three turns. This is enough to allow the **spar** to be moved. Once the **thumb screws** are loose, grasp the **chest bridge** in the right hand and the **waist panel** in the left hand. Gently tug them apart and the two parts will slide easily.



Hold the lower section of the Steadicam **arm** (10) in the right hand and pull the **connecting pin** (11). It is the **steel pin** with the **ring** attached. Line up the two sections of the Steadicam Merlin **arm**. One section nests just inside the other. Some find this easier if the sections are held as shown, others prefer to lay the sections on a table.



The **arm** is not properly inserted in this view. Note the shiny **steel back plate** pressed against the **bolts**. The **thumb screws** must be turned out far enough to allow the **socket** to insert fully.



The **arm** is properly inserted in this view, with the **thumb screw bolts** nested in the slight groove in the **steel back plate**. Now the **screws** can be adjusted for each operator.



**Wheels** (13) on **arm mount** are used to fit the side-to-side angle of the Steadicam Merlin **arm** to the individual user.